

Verifying Probabilistic Correctness in Isabelle with pGCL

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler



Australian Government
Department of Broadband,
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- Stochastic Behaviour in Systems
- Functional vs. Probabilistic Verification
- pGCL in Isabelle/HOL
- Example: Lattice-Lottery Scheduler

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Functional vs. Probabilistic Verification

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Sources of Uncertainty



We like certainty.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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The L4.verified proof tells us that if its assumptions are satisfied, seL4 will *definitely* not crash.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Lattice-Lottery
Scheduler

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Lattice-Lottery
Scheduler

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

Probability Refines Nondeterminism



Classical nondeterminism is the ultimate in pessimism:
Anything that *can* happen *will* happen.

If we know how events are distributed, we can do better.

Probabilistic models are a halfway-house between full
nondeterminism and full predictability.

Probabilistic guarantees are relevant both for security, and
for reliability.

Our current work is on probabilistic security guarantees.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

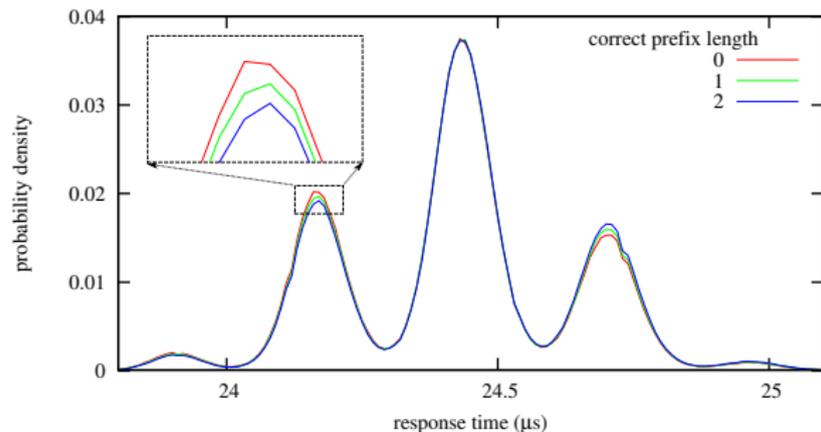
Example:
Lattice-Lottery
Scheduler

Why is this relevant in systems?



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Feed a secret string and a guess to strcmp:



Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

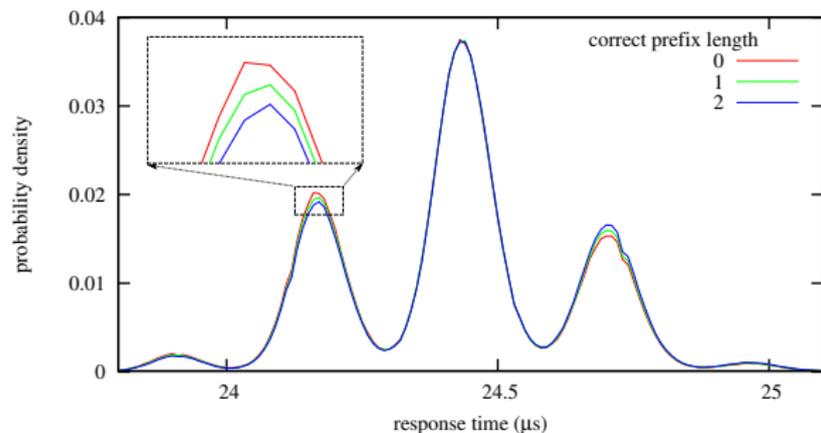
pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

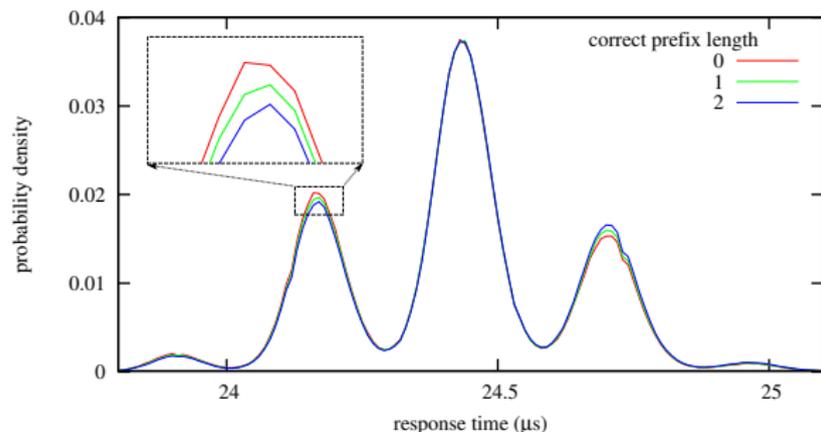
pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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Feed a secret string and a guess to strcmp:



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How bad is it? How can we mitigate it?

How will it behave in a larger system?

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

Probabilistic verification can help us answer these questions.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

Probabilistic verification can help us answer these questions.

We want to show something like:

$$\wp ((r, \tau) := \text{strcmp}(g, s); \\ g := \text{cleverness}(r, \tau, g) \mid (g = s) \leq 2^{-100}$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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Formulating this rigorously is the subject of our existing work.

Mechanising this work in Isabelle/HOL ensures our reasoning is sound, and scalable to large problems.

We use pGCL, an extension of Dijkstra's GCL with probability.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler



- Stochastic Behaviour in Systems
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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

How do we interpret this?

$$\{x = 0\} y := x^2 \{y = x\}$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

How do we interpret this?

$$\{x = 0\} y := x^2 \{y = x\}$$

This relates a program to an annotation.

If $x = 0$ holds before, then $y = x$ holds afterwards.

Is $x = 0$ maximal?

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Lattice-Lottery
Scheduler

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Lattice-Lottery
Scheduler

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$\{x = 0 \vee x = 1\}$ is maximal,
it is the *weakest precondition* of $\{y = x\}$.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Lattice-Lottery
Scheduler

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$$\wp a Q \equiv \sup \{P \mid P a Q\}$$

$$\{R\} \leq \{S\} \equiv R \vdash S \equiv \forall s. R s \rightarrow S s$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

Nondeterminism allows us to underspecify a program.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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Algebraically: $\wp (a \sqcap b) Q = \wp a Q \cap \wp b Q$

Thus $P = \{x = 0 \vee x = 1\} \cap \{x = 0\} = \{x = 0\}$.

We are treating annotations as sets.



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We can still order these: $\llbracket P \rrbracket \leq \llbracket Q \rrbracket \equiv \forall s. \llbracket P \rrbracket s \leq \llbracket Q \rrbracket s$

Note: $\wp (a \sqcap b) \llbracket Q \rrbracket = \min (\wp a \llbracket Q \rrbracket) (\wp b \llbracket Q \rrbracket)$.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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The ‘weakest precondition’ is the *least* value that the postcondition may take, from a given initial state.

It is the pessimistic *expected value* of the postcondition.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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It is the pessimistic *expected value* of the postcondition.

These quantitative predicates are called *expectations*.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler



What if the demon were a gambler?

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

What if the demon were a gambler?

$a \text{ }_{1/2} \oplus b$ means ‘flip a coin — if heads a otherwise b ’.

What should $\wp (y := x^2 \text{ }_{1/2} \oplus y := 2x) (y = x)$ be?

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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For an expectation, we’d take the weighted average:

$$\wp (a \oplus_p b) F = p \times \wp a F + (1 - p) \times \wp b F$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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$\wp (a \oplus_p b) (y = x) s$ is the *probability* that, if we start in state s , $y = x$ holds in the final state.

$\wp (a \oplus_p b) (y = x) 0 = 1$ and $\wp (a \oplus_p b) (y = x) 1 = 1/2$.

All other values are zero.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

How about this?

$$E = \wp \left(\left((y := x^2 \text{ }_{1/2} \oplus y := 2x) \sqcap \right. \right. \\ \left. \left. (y := x^2 \text{ }_{1/3} \oplus y := 2x) \right) (y = x) \right)$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler



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Simply apply both rules:

$$E x = \min \left(\frac{1}{2} \times \llbracket x = 0 \vee x = 1 \rrbracket + \frac{1}{2} \times \llbracket x = 0 \rrbracket \right. \\ \left. \frac{1}{3} \times \llbracket x = 0 \vee x = 1 \rrbracket + \frac{2}{3} \times \llbracket x = 0 \rrbracket \right)$$

This time, $E 0 = 1$ and $E 1 = 1/3$.



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This time, $E 0 = 1$ and $E 1 = 1/3$.

$E x$ is the *minimum* probability that $y = x$ will hold.

These are basics of pGCL (Morgan & McIver, 2004).

It's a formal model of computation incorporating probability and nondeterminism.

In the remainder of the talk I will introduce our mechanisation in Isabelle/HOL, and our work on the probabilistic verification of systems software.

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

The pGCL package provides a shallow embedding into HOL.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

The pGCL package provides a shallow embedding into HOL.
Expectations use the standard real number type:

$$E :: \sigma \Rightarrow \mathbb{R}$$

This allows us to use existing results directly.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Lattice-Lottery
Scheduler

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Expectations are nonnegative and bounded:

$$\text{nneg } E \equiv \forall s. 0 \leq E s \quad \text{bounded } E \equiv \exists b. \forall s. E s \leq b$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Lattice-Lottery
Scheduler

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The state space need not, in general, be finite.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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$$\wp a :: (\sigma \Rightarrow \mathbb{R}) \Rightarrow \sigma \Rightarrow \mathbb{R}$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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$$\forall P b. \text{bounded_by } b P \wedge \text{nneg } P \rightarrow \\ \text{bounded_by } b (t P) \wedge \text{nneg } (t P)$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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$$\forall P Q. (\text{sound } P \wedge \text{sound } Q \wedge P \vdash Q) \longrightarrow (t P) \vdash (t Q)$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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$$\forall P c s. (\text{sound } P \wedge 0 < c) \longrightarrow c \times t P s = t (\lambda s. c \times P s) s$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

A few primitives



Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

$\text{Abort} \equiv \lambda ab P. \text{if } ab \text{ then } \lambda s. 0 \text{ else } \lambda s. \text{bound_of } P$

We model both strict (WP) and liberal (WLP) semantics.
All these primitives are healthy.

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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$a \text{ }_p \oplus b \equiv \lambda ab P s. p \times (a \text{ } ab \text{ } P \text{ } s) + (1 - p) \times (b \text{ } ab \text{ } P \text{ } s)$

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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$a \sqcap b \equiv \lambda ab P s. \min (a \text{ } ab \text{ } P \text{ } s) (b \text{ } ab \text{ } P \text{ } s)$

$a \text{ } p \oplus b \equiv \lambda ab P s. p \times (a \text{ } ab \text{ } P \text{ } s) + (1 - p) \times (b \text{ } ab \text{ } P \text{ } s)$

$\wp a \equiv a \text{ True}$

We model both strict (WP) and liberal (WLP) semantics.

All these primitives are healthy.

The shallow embedding makes it easy to embed the L4.verified nondeterministic monad:

$$\text{Exec} :: (\sigma \Rightarrow (\alpha \times \sigma) \text{ set}) \Rightarrow \text{bool} \Rightarrow (\sigma \Rightarrow \mathbb{R}) \Rightarrow \sigma \Rightarrow \mathbb{R}$$
$$\text{Exec } M \equiv \lambda ab R s. \text{glb } \{R (\text{snd } sa). sa \in M s\}$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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We lift Hoare triples to probabilistic entailments:

$$\frac{\text{WP_EXEC} \quad \{P\} \text{ prog } \{\lambda r s. Q s\} \quad \forall s. \text{prog } s \neq \{\} \quad \exists s. P s}{\ll P \gg \vdash \wp \text{ prog } \ll Q \gg}$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler



- Stochastic Behaviour in Systems
- Functional vs. Probabilistic Verification
- pGCL in Isabelle/HOL
- Example: Lattice-Lottery Scheduler

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler



One of the principle tools in verification is *refinement*.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

One of the principle tools in verification is *refinement*.
A refinement relation allows us to transfer properties from
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$$\frac{a \sqsubseteq b \quad E \vdash \wp.a.F}{E \vdash \wp.b.F}$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Lattice-Lottery
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In pGCL, an implementation establishes any property with at least as great a probability as its specification.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

An approach to efficiently eliminating leaks through shared state e.g. caches.

Only switch to a domain with higher clearance, or to the downgrader, which clears the cache:

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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The security property:

$$\forall c, n. (c, n) \in S \rightarrow \text{sec_class}.c \leq \text{sec_class}.n \vee \\ n = \text{downgrader}$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

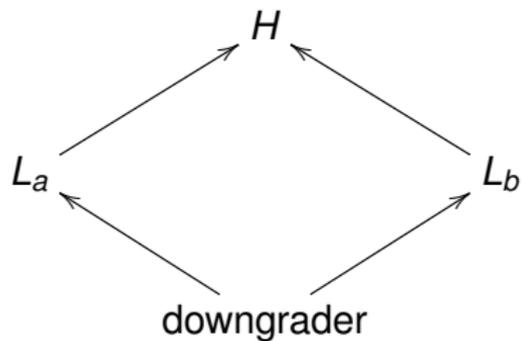


Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler



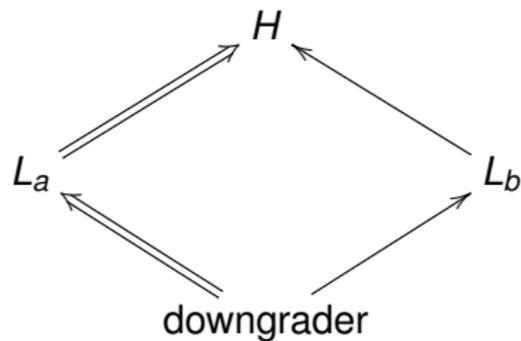


Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler



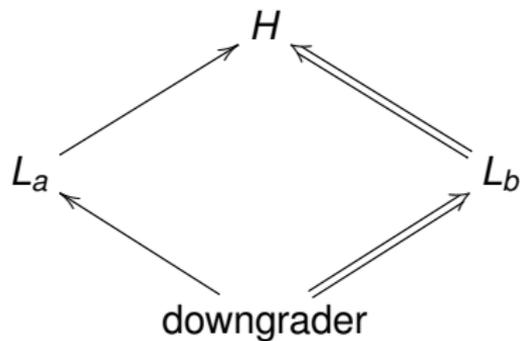


Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler



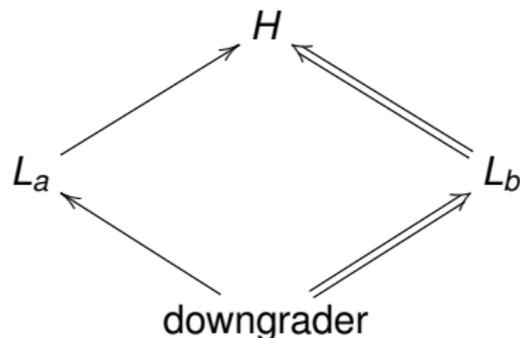


Stochastic
Behaviour in
Systems

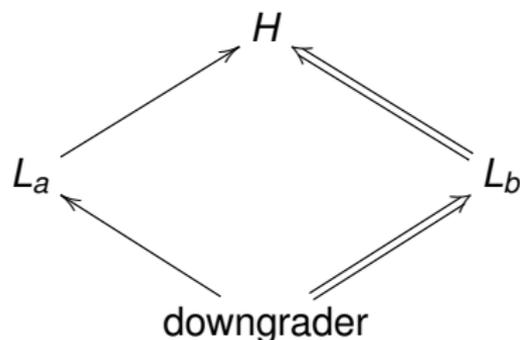
Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler



A single-period schedule cannot include both L_a and L_b .



A single-period schedule cannot include both L_a and L_b .

A nondeterministic scheduler might simply always pick L_b .

Randomised Lattice Scheduling



We'd still like to have asymptotic fairness between domains.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

Randomised Lattice Scheduling



We'd still like to have asymptotic fairness between domains.

Start by randomising:

$$\text{scheduleR} \equiv cd : \in \text{UNIV at } (\lambda s n. T (cd, n))$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Lattice-Lottery
Scheduler

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If the matrix T satisfies:

$$\forall c n. 0 < T (c, n) \rightarrow (c, n) \in S$$

we have refinement, $\text{scheduleL} \sqsubseteq \text{scheduleR}$.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Lattice-Lottery
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This scheduler is a Markov process, and if T is irreducible and positive recurrent, there exists a stationary distribution.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

An efficient implementation might use a lottery:

```
scheduleM t ≡ do
  c ← gets cd; l ← gets lottery;
  let n = l c t in modify(λs. s(cd := n))
od
```

The lottery has type: `domain ⇒ word32 ⇒ domain`.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Lattice-Lottery
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od
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The lottery has type: $\text{domain} \Rightarrow \text{word32} \Rightarrow \text{domain}$.

We chain in probability from above:

```
scheduleC ≡ t from UNIV at  $2^{-32}$  in Exec (scheduleM t)
```

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

We cannot show that $\text{scheduleR} \sqsubseteq \text{scheduleC}$, as they operate on different state spaces:

record stateA = $cd :: \text{domain}$

record stateC = $cd :: \text{domain},$

lottery :: $\text{domain} \Rightarrow \text{word32} \Rightarrow \text{domain}$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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The lottery is an implementation detail, only cd matters.

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Take the natural projection: $\phi :: \text{stateC} \Rightarrow \text{stateA}.$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

We define *data refinement*, $\sqsubseteq_{\phi, Pre}$:

$$\frac{a \sqsubseteq_{\phi, Pre} b \quad E \vdash \wp a F \quad Pre s}{(E \circ \phi) s \vdash \wp b (F \circ \phi) s}$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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If the ticket distribution represents the transition matrix:

$$LR \ s \equiv \forall c, n. T(c, n) = \sum_{t. \text{lottery } s \ c \ t=n} 2^{-32}$$

we have another refinement step:

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Lattice-Lottery
Scheduler

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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$$\text{scheduleL} \sqsubseteq \text{scheduleR} \sqsubseteq_{\phi, LR} \text{scheduleC}$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

Attaching the Kernel



Finally, we attach a kernel model:

```
stepKernel  $\equiv$  callKernel; scheduleC
```

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

Finally, we attach a kernel model:

$$\text{stepKernel} \equiv \text{callKernel}; \text{scheduleC}$$

We need only a few high-level properties, including:

$$\{cd = d\} \text{callKernel} \{cd = d\}$$

which is a specification in the L4.verified Hoare logic, from which we establish:

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Lattice-Lottery
Scheduler

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The kernel may modify the lottery!

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

Example:
Lattice-Lottery
Scheduler

If the kernel additionally preserves the lottery relation:

$$\{LR\} \text{ callKernel } \{LR\}$$

then we have the full refinement chain:

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Lattice-Lottery
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$$\text{scheduleL} \sqsubseteq \text{scheduleR}$$

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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$$\text{scheduleL} \sqsubseteq \text{scheduleR} \sqsubseteq_{\phi, LR} \text{stepKernel}$$

The kernel implements a fair, secure scheduler.

Summary



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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

**Example:
Lattice-Lottery
Scheduler**

We have:

Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Lattice-Lottery
Scheduler

We have:

- Motivated probabilistic verification for systems.

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- Mechanised pGCL in Isabelle/HOL.

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- Motivated probabilistic verification for systems.
- Mechanised pGCL in Isabelle/HOL.
- Verified a randomised scheduler.



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Stochastic
Behaviour in
Systems

Functional vs.
Probabilistic
Verification

pGCL in
Isabelle/HOL

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Lattice-Lottery
Scheduler**

Questions?